

Recipes for writing algorithms to retrieve columnar
water vapor for 3-band multi-spectral data

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Introduction

Water vapor retrievals have four following steps in common:

1. Run a radiative transfer (RT) algorithm for a range of water vapor values and a particular observation geometry,
2. Compute sensor band-averaged radiances,
3. Compute a non-linear fit of channel ratios (e.g. CIBR or APDA) as a function of water vapor,
4. Apply the inverse fit to retrieve columnar water vapor as a function of channel ratio.

Transmission based CIBR recipe

Total spectral attenuation due to water vapor alone is given by:

$$T_{H_2O}(\nu, CW) = T_{H_2O, \text{sun} \rightarrow \text{ground}}(\nu, CW) T_{H_2O, \text{ground} \rightarrow \text{sensor}}(\nu, CW), \quad (1)$$

where ν is the wavenumber in cm^{-1} and CW is the columnar water vapor in g/cm^2 .

The steps for CIBR retrieval are:

1. The default *TAPE5* for MODTRAN4 was:

```

T   a   2   0   0   0   0   0   0   0   0   0   0   0   0.001   0.00
F   OT   2  355.000  Gb.bb
    1   0   0   0   0   0   0.000   0.000   0.000   0.000   0.000
ccc.ccc   d.ddd 0.000   eee.eee   0.000   0.000   0.000   0
    0.8000   1.1000   0.0100   0.0200           M   A
    0
  
```

where:

Atmosphere type: $a = 1$ =Tropical Atmosphere, 2 =Midlatitude Summer, 3 =Midlatitude Winter, 4 =Subarctic Summer, 5 =Subarctic Winter, 6 =1976 US Standard,

Water vapor: $b.bb = 0.05, 0.1, 0.2, 0.3, .5, 0.75, 1., 1.25, 1.5, 1.75, 2., 2.5, 3., 3.5, 4., 4.5, 5., 6., 6.5, 7. \text{ and } 8. g/cm^2,$

Sensor height: $ccc.ccc = 100.00 \text{ km},$

Ground altitude: $d.ddd = \text{read from data base}$

Phase angle: $eee.eee = 180^\circ - \theta$ where θ is either the sun or view zenith angle.

2. Run MODTRAN4 in transmission mode and read transmission from TAPE7 and compute band-averaged transmission $T_{i,H_2O}(CW)$:

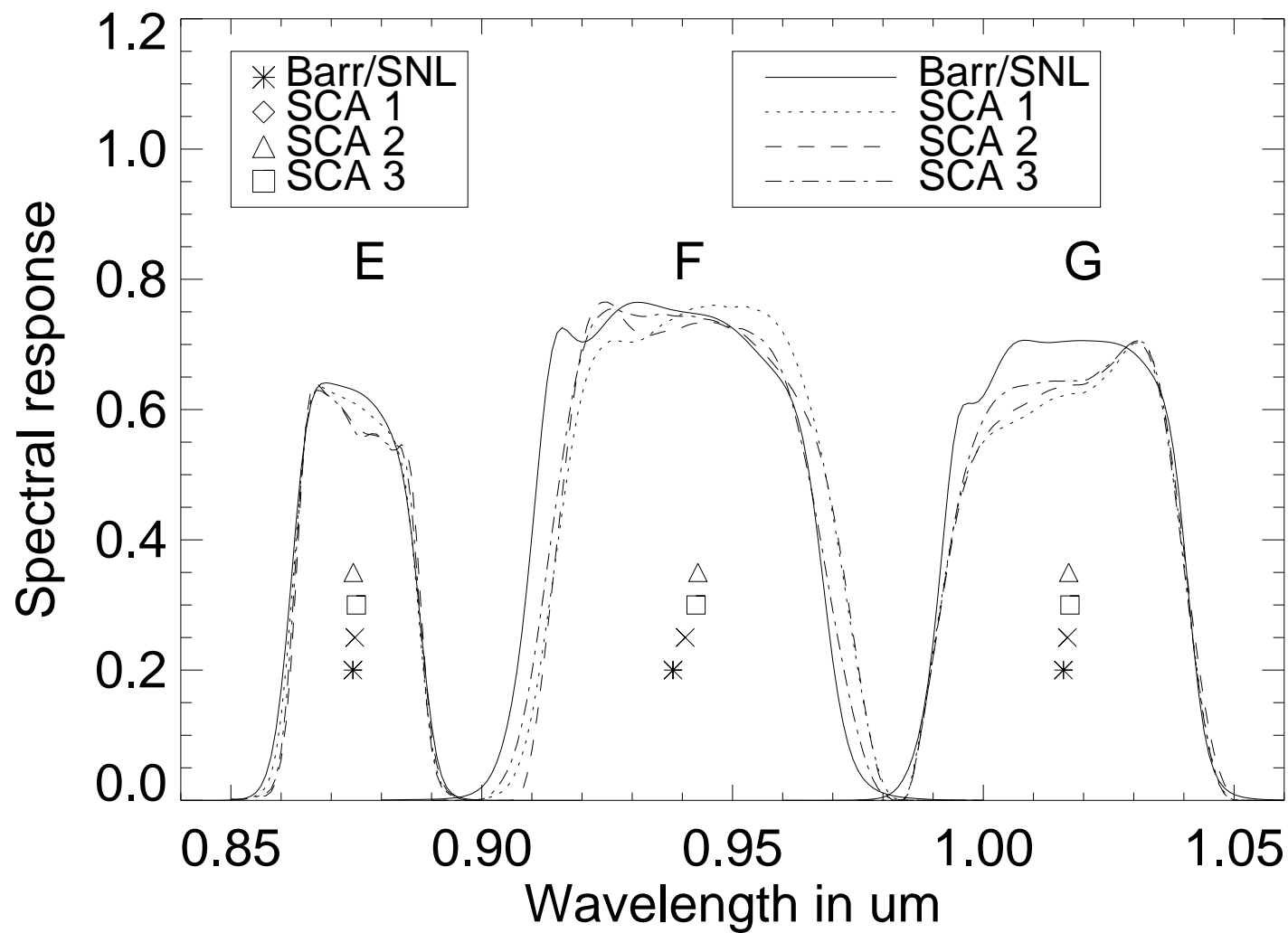
$$T_{i,H_2O}(CW) = \frac{\int_{\nu(i)_a}^{\nu(i)_b} R_i(\nu) T_{H_2O}(\nu, CW) d\nu}{\int_{\nu(i)_a}^{\nu(i)_b} R_i(\nu) d\nu}, \quad (2)$$

where $R_i(\nu)$ is the spectral response of the i -th channel, $i = \{E, F, G\}$.

Two types of spectral responses are used for MTI:

- (a) Barr/SNL: filter transmissions measures at room temperature & nadir and converted by SNL model to off-nadir cones of $f = 3.5$ telescope at 75° K.
- (b) LANL measured dual monochromator spectral responses (new).

For MTI spectral responses for water vapor channels E, F and G are:



Center wavelengths $\lambda_{c,i}$ with:

$$\lambda_{c,i} = \frac{10000}{\nu_{c,i}}, \quad \text{where} \quad \nu_{c,i} = \frac{\int_{\lambda(i)_a}^{\lambda(i)_b} \lambda R_i(\lambda) d\lambda}{\int_{\lambda(i)_a}^{\lambda(i)_b} R_i(\lambda) d\lambda}. \quad (3)$$

- The center wavelengths for the Barr/SNL filter functions are: $\lambda_{c,E} = 0.874310\mu m$, $\lambda_{c,F} = 0.93813\mu m$ and $\lambda_{c,G} = 1.01599\mu m$.
- The bandwidths for the Barr/SNL filter functions are $BW_E = 0.0160052\mu m$, $BW_F = 0.0428301\mu m$ and $BW_G = 0.0340523\mu m$.

CIBR look-up-table construction:

$$CIBR_{RT} = \frac{T_{F,H_2O}(CW_{RT})}{w_1 T_{E,H_2O}(CW_{RT}) + w_2 T_{G,H_2O}(CW_{RT})} \quad (4)$$

Interpolation scheme:

$$x = \sqrt{CW_{RT}} \quad \text{and} \quad y = \log_{10}[CIBR_{RT}(CW_{RT})]. \quad (5)$$

Using a linear fit $Q(z) = a_0 + a_1 z$ to the pair (x, y) we can now generate a continuous LUT with $CW_{RT} = x^2$ and $CIBR_{RT} = 10^{Q(CW_{RT})}$.

3. To compute the CIBR from MTI data we use band-averaged radiance values L_i in the following expression (for detailed derivations see Schl pfer et al, (1996)):

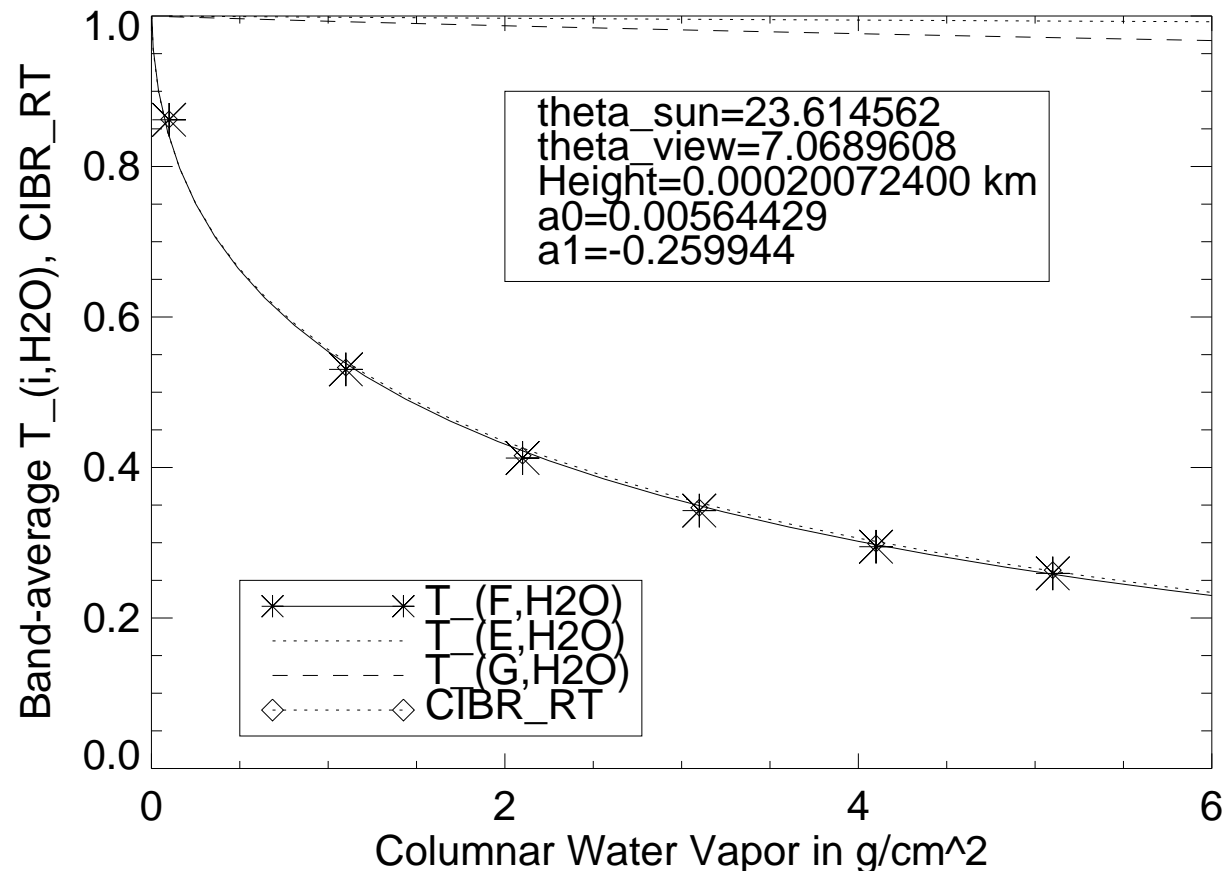
$$CIBR_{data} = \frac{L_F}{w_1 L_E + w_2 L_G}, \quad \text{where} \quad (6)$$

where:

$$w_1 = \frac{\lambda_{c,G} - \lambda_{c,F}}{\lambda_G - \lambda_E} \quad \text{and} \quad w_2 = \frac{\lambda_{c,F} - \lambda_{c,E}}{\lambda_G - \lambda_E}.$$

For MTI using the Barr/SNL filter functions we have $w_1 = 0.5495$ and $w_2 = 0.4505$.

Example of fitting the band-averaged water vapor transmissions $T_{i,H_2O}(CW_{RT})$ and $CIBR_{RT}(CW_{RT})$ for a MTI data set:



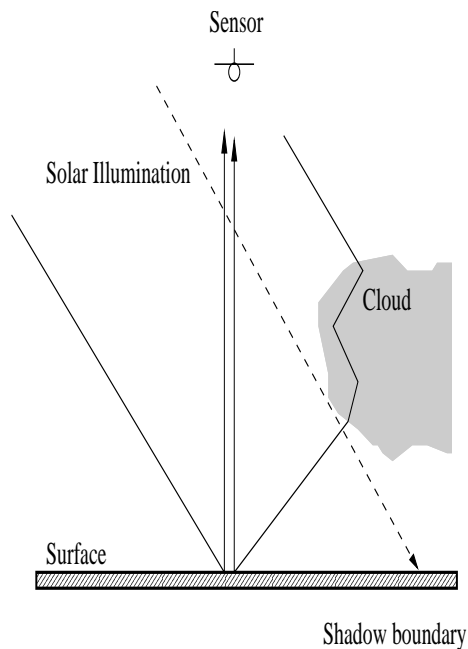
4. To compute the columnar water vapor CW_{data} from $CIBR_{data}$ the following inverse function is used:

$$CW_{data} = [P(\log_{10}(CIBR_{data}))]^2, \quad (7)$$

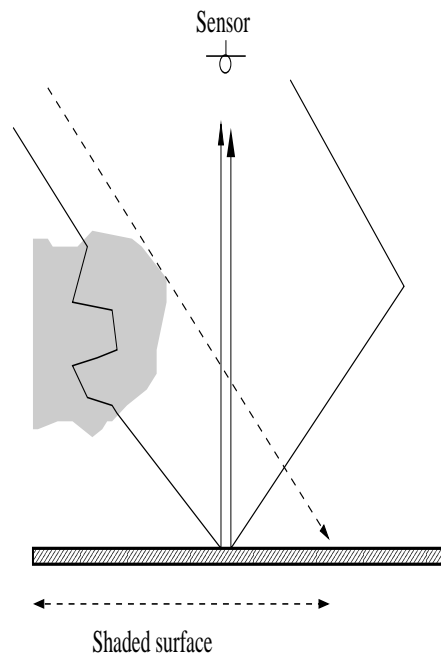
where $P(z) = b_0 + b_1 z$ is a linear fit to $x = \log_{10}[CIBR_{RT}(CW_{RT})]$ and $y = \sqrt{CW_{RT}}$.

The advantages of this method are:

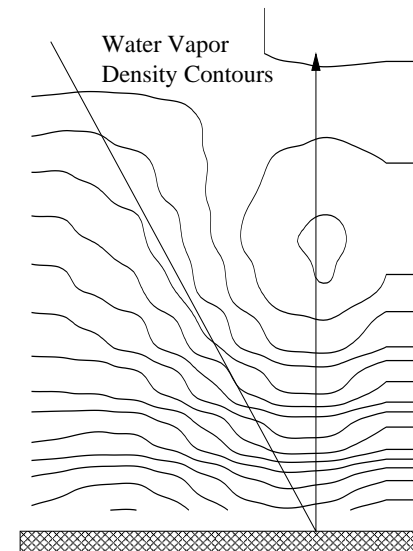
1. Simpler to implement and much faster to run than radiance based CIBR.
2. In principle can handle cases:
 - (a) The surface receives direct sunlight and light scattered from the side of a cloud.
 - (b) The surface is in a cloud shadow and we receive light scattered through the cloud.
 - (c) The atmosphere is not horizontally homogeneous, e.g. devise a retrieval where the water vapor profiles are iteratively adjusted for both paths.



a



b



c

Radiance based CIBR recipe

1. Run MODTRAN4 in radiance mode for a specific CW_{RT} , atmosphere (tropical, mid-latitude summer, mid-latitude winter, sub-arctic summer, sub-arctic winter) and aerosol model (rural, maritime or urban). The visibility was set to 23 km and the surface reflectance to 0.45. The multiple scattering code used is the two-stream Isaacs method.

Calculate $CIBR_{RT}(CW_{RT})$ using the instrument specific response functions $R_i(\nu)$:

$$CIBR_{RT}(CW_{RT}) = \frac{L_F}{w_1 L_E + w_2 L_G}, \quad \text{where } L_i = \frac{\int_{\nu(i)_a}^{\nu(i)_b} R(\nu) L(\nu) d\nu}{\int_{\nu(i)_a}^{\nu(i)_b} R_i(\nu) d\nu}, \quad (8)$$

where $L(\nu)$ is obtained from MODTRAN TAPE7.

2. Repeat 1 for 10 times to create a look-up table of equally spaced $[CW_{RT}, CIBR(CW_{RT})]$ from a minimum to a maximum value of CW_{RT} .
3. For each pixel calculate $CIBR_{data}$ ratio from sensor data using eq (8) where the measured radiances are used in L_F , L_E and L_G .
4. For each pixel interpolate $CIBR_{data}$ to determine the appropriate CW for that pixel from the look-up-table $[CW_{RT}, CIBR_{RT}(CW_{RT})]$.

APDA recipe

In contrast to CIBR, APDA corrects for path radiance in the absorption band by using MODTRAN4 determined path radiance as a function of water vapor column amount.

Basic principle: Iterate between two coupled equations, one based on a 3-channel ratio and the other on a function $f_{RT}()$ to convert the ratio into columnar water vapor:

$$\begin{aligned} APDA_{data} &= \frac{L_{F,data} - L_{F,Path,RT}(CW_{data})}{w_1(L_{E,data} - L_{E,Path,RT}) + w_2(L_{G,data} - L_{G,Path,RT})} \quad (9) \\ CW_{data} &= f_{RT}(APDA_{data}) \end{aligned}$$

where:

- $L_{F,Path}(CW_{data}) = c_0 + c_1 CW_{data} + c_2 CW_{data}^2$ is a second order polynomial fit to the values of $L_{F,Path}$ as a function of CW_{RT} calculated from MODTRAN4.
- $L_{E,Path}$ and $L_{G,Path}$ are assumed to be water vapor independent, due to their position outside the water vapor feature at 940nm.

Notes:

- $APDA_{RT}$ is derived using band averaged radiance values from MODTRAN4 run $\rho_{surface} = 0.45$ as a function of CW_{RT} .
- This $APDA_{RT}(CW_{RT})$ is interpolated so that a CW_{data} value is returned for each value of $APDA_{data}$.

APDA procedure steps:

1. Run MODTRAN4 for a value of CW_{RT} .
2. Compute L_i and $L_{i,Path}(\nu)$ by convolving the top of atmosphere radiance $L(\nu)$ and path radiance $L_{Path}(\nu)$ values with response functions $R_i(\nu)$ for $i = \{E, F, G\}$.
3. Repeat 1 and 2 to create $L_E(CW)$, $L_F(CW)$, $L_G(CW)$, $L_{E,Path}$, $L_{F,Path}(CW)$, and $L_{G,Path}$.
4. Create a lookup table $[CW_{RT}, APDA_{RT}(CW_{RT})]$.
5. Create a quadratic fit to the look-up table $[CW_{RT}, L_{F,Path}(CW_{RT})]$.
6. Using eq (10) calculate $APDA_{data}$ for an initial value of CW_{data} , e.g. the neighbor pixel.
7. Find CW_{data} value from $f_{RT}(APDA_{RT}(CW_{data}))$
8. Convergence is achieved when the previous estimated CW_{data} value is within 1×10^{-3} of the current value. Otherwise, iterate, so that the new CW_{data} becomes the previous estimated CW_{data} value.

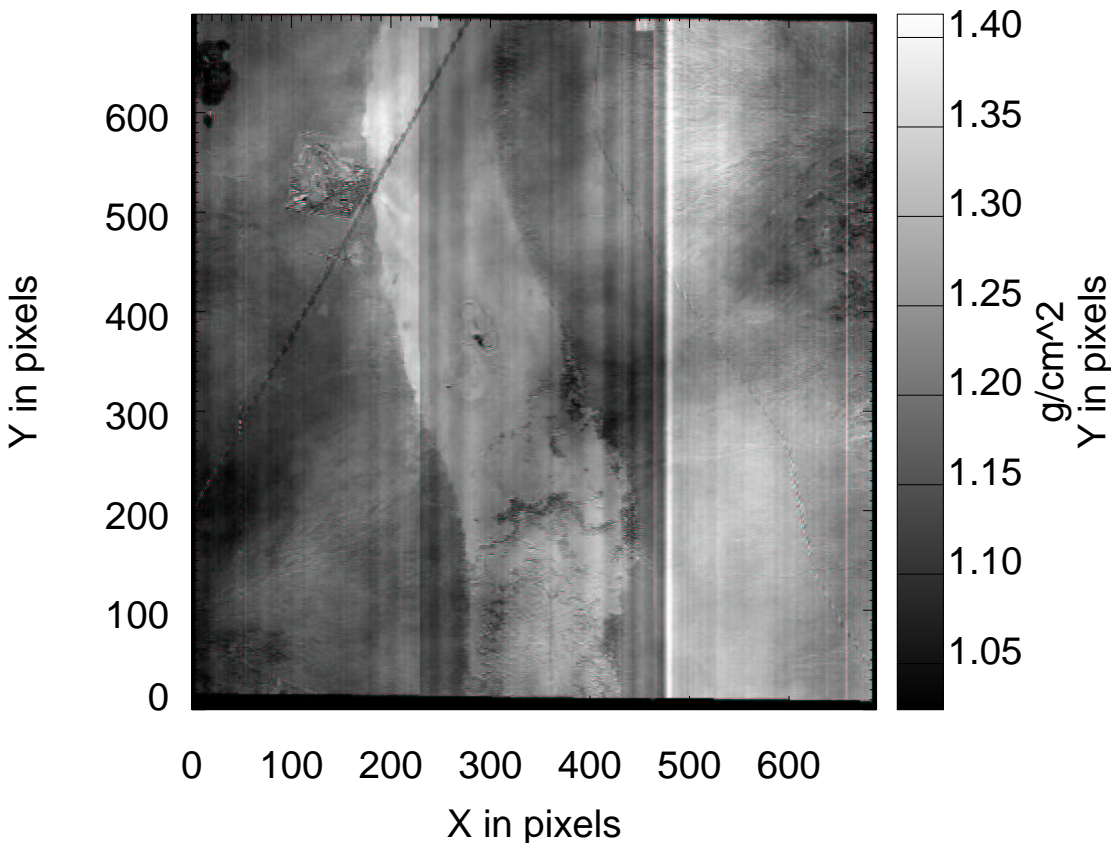
Notes:

1. Typically 3 iterations are sufficient to converge.
2. Need good information on aerosols (aerosol type and optical depth).
3. Sub-pixel registration errors cause erroneous values near water-land boundaries

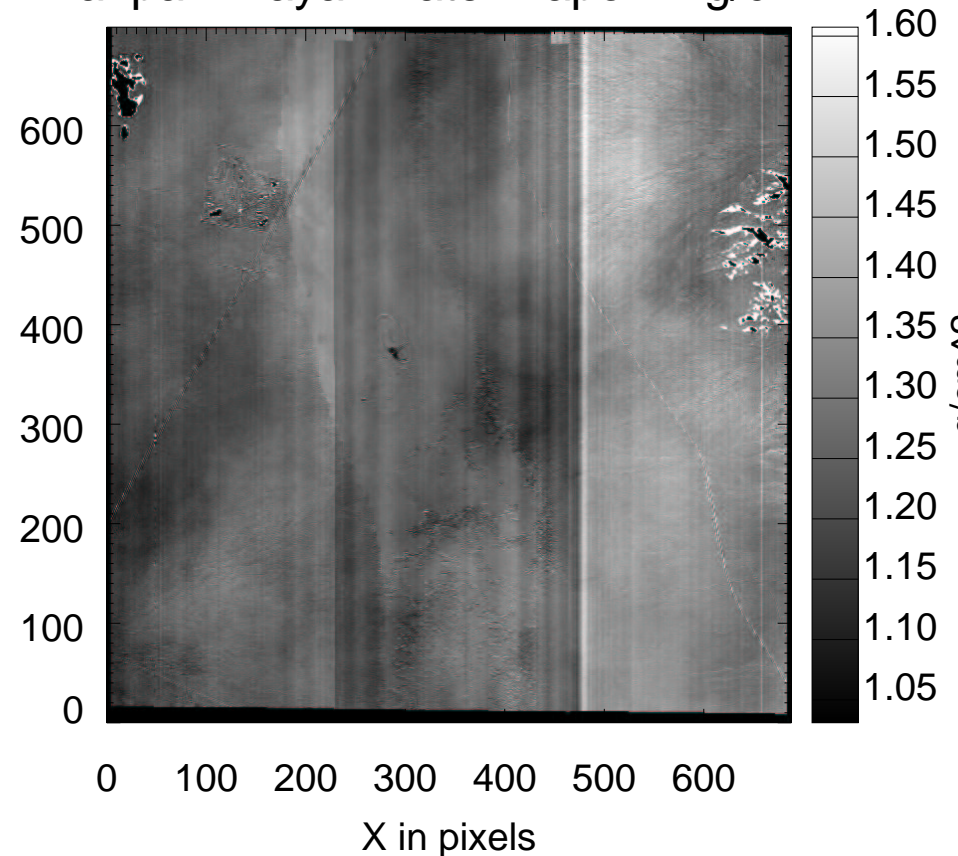
Comparison of results: for details see paper by Hirsch et al, 2001

Ivanpah Playa in Nevada for September 15, 2000. The sun-photometer measured water vapor amount was 1.35 g/cm^2

Ivanpah Playa: Water Vapor in g/cm^2



Ivanpah Playa: Water Vapor in g/cm^2



Note: Boundary between bright playa and surrounding area disappears in APDA.

Conclusions

- The transmission based CIBR reports higher values than the radiance based algorithm.
- Described first automated implementation of APDA for MTI.
- APDA performs much better over dark targets than CIBR when aerosol properties known.

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